

Big Data Analysis for Road Accident Risk Prediction in Graz

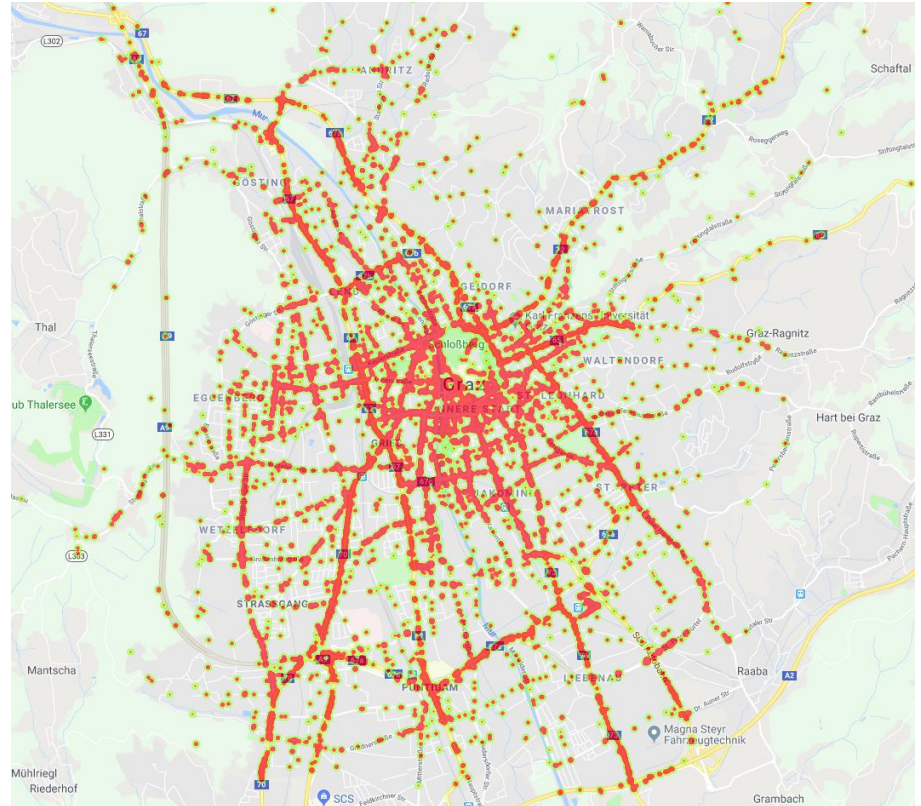
Michael Jantscher

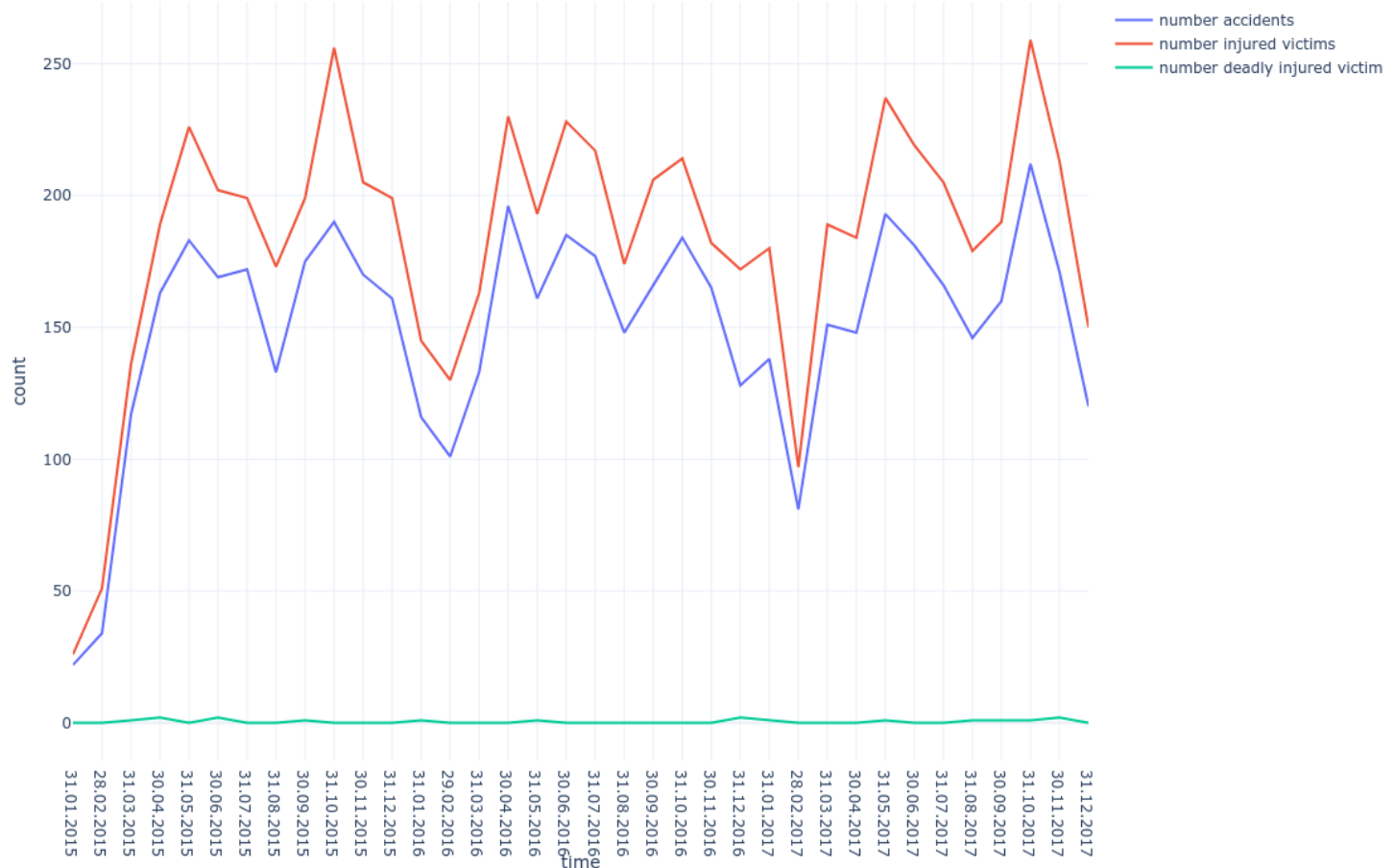
Supervisors:
Dipl.-Ing. Dr.techn. Roman Kern

Graz, 19th March 2020

- Previous work
 - Key factors contributing to road accidents
 - Case Study research on temporal and spatial data
 - Accident severity analysis based on the Austrian crash data set
- Goal
 - Exploratory data analysis and statistical tests
 - Missing value imputation of traffic flow data
 - City wide traffic accident likelihood estimation

- Tracked by Austrian police officers
- 5416 accidents between 2015 – 2017
- Constant accident rate





- Vehicle crash data
- Road Network Graphs
 - OpenStreetMap (OSM) [1]
 - Graphenintegrations-Plattform (GIP) [2]
- Population specific data
- Weather data
- Traffic flow

[1] OpenStreetMap <https://wiki.openstreetmap.org> (Accessed on: 2020-03-08)

[2] GIP <http://gip.gv.at> (Accessed on: 2020-03-08)

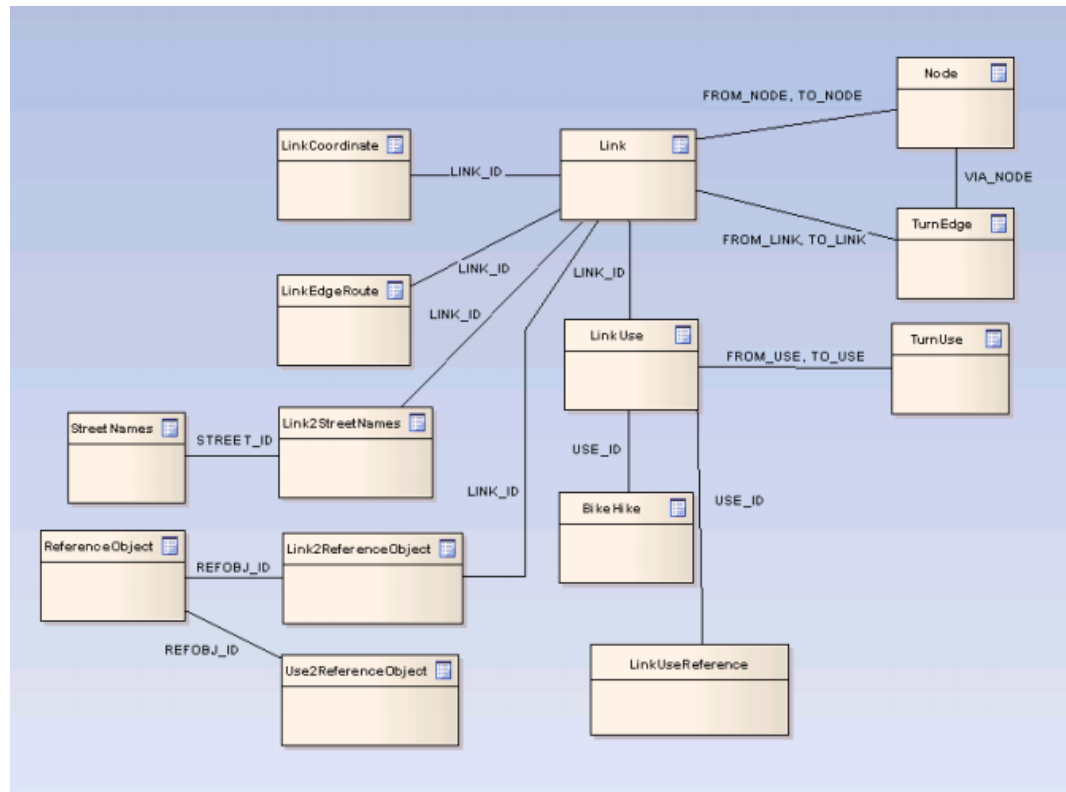
- 5416 records between 2015 and 2017
- Attributes:
 - Occurrence location (GPS + Region information)
 - Occurrence time
 - Car specific data
 - Street specific data
 - Weather conditions
 - Injury severity
 - ...

- OpenStreetMap (OSM)
 - OSMNX [3] download of drivable roads in Graz
 - Routable graph

Feature	Description
osmid	unique street vertex identifier
lanes	representing number of lanes
length	representing the street segments length
maxspeed	maximum speed value
name	street name
oneway	True if there is an access restriction for this street segment

[3] Boeing, G. 2017. "OSMnx: New Methods for Acquiring, Constructing, Analyzing, and Visualizing Complex Street Networks." Computers, Environment and Urban Systems 65, 126-139.

- Graphenintegrations-Plattform (GIP)



Source: http://www.gip.gv.at/assets/downloads/1912_dokumentation_gipat_ogd.pdf

- Feature Engineering
 - Closeness Centrality of road links [4]

$$C(u) = \frac{n - 1}{\sum_{v=1}^{n-1} d(v, u)}$$

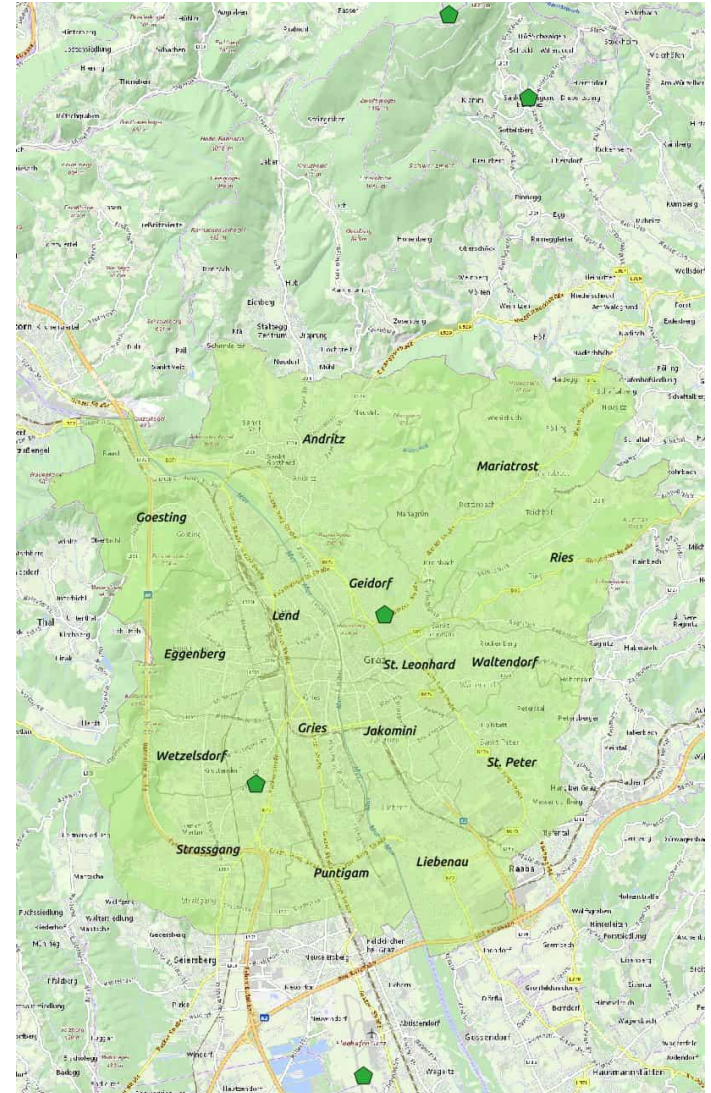
- Road Curvature

$$curve_{link} = \frac{length(link)}{d(link_{start}, link_{end})}$$

- Road Slope
- Junction plateau definition

[4] Linton C. Freeman: Centrality in networks: I. Conceptual clarification. Social Networks 1:215-239, 1979.
<http://leonidzhukov.ru/hse/2013/socialnetworks/papers/freeman79-centrality.pdf>

- ZAMG weather stations
- Temperature and Rainfall
- Match weather data with road links
 - Inverse distance weighting

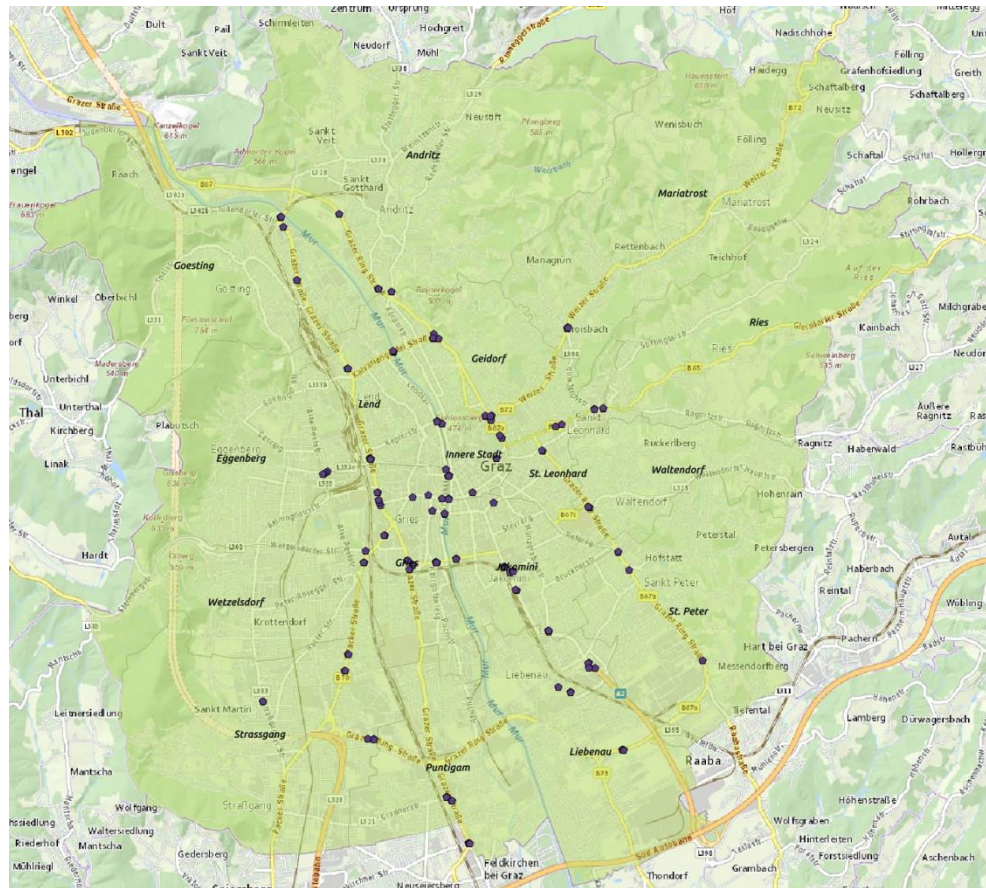


- Open Government Data Austria [5]
 - Population by district and age export
- Population density by district

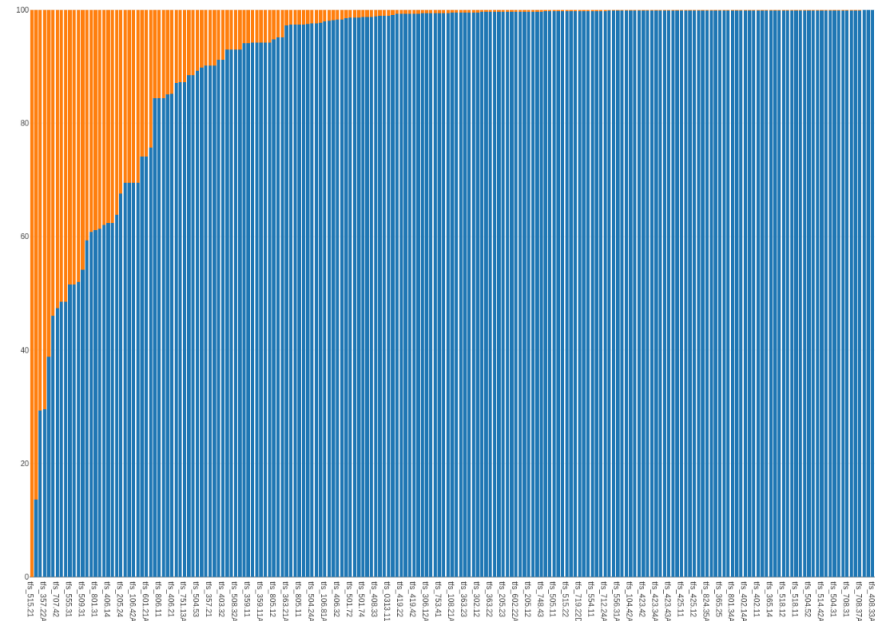
$$\text{density}(\text{district}) = \frac{\text{population}(\text{district})}{\text{area}(\text{district})}$$

[5] Open Data Austria <https://www.data.gv.at/> (Accessed on: 2020-03-08)

- Department of Roads Graz



- Only 15% Missing Values (MV) for more than 170 stations
- Missing Value series
 - 61% MV series are lower than 4 samples
 - Peaks at 26, 84 and 96 consecutive MV
- Univariate vs Multivariate Imputation

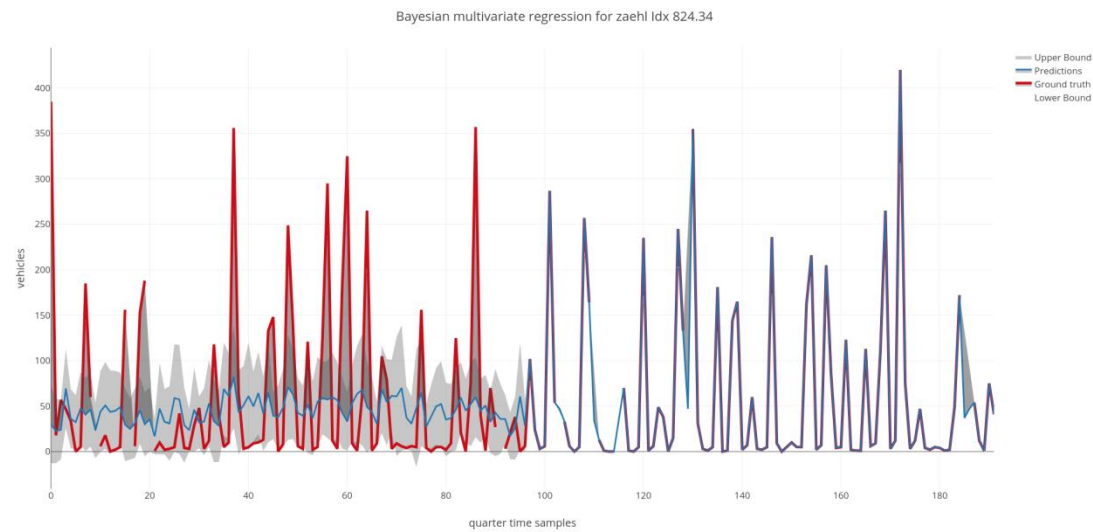
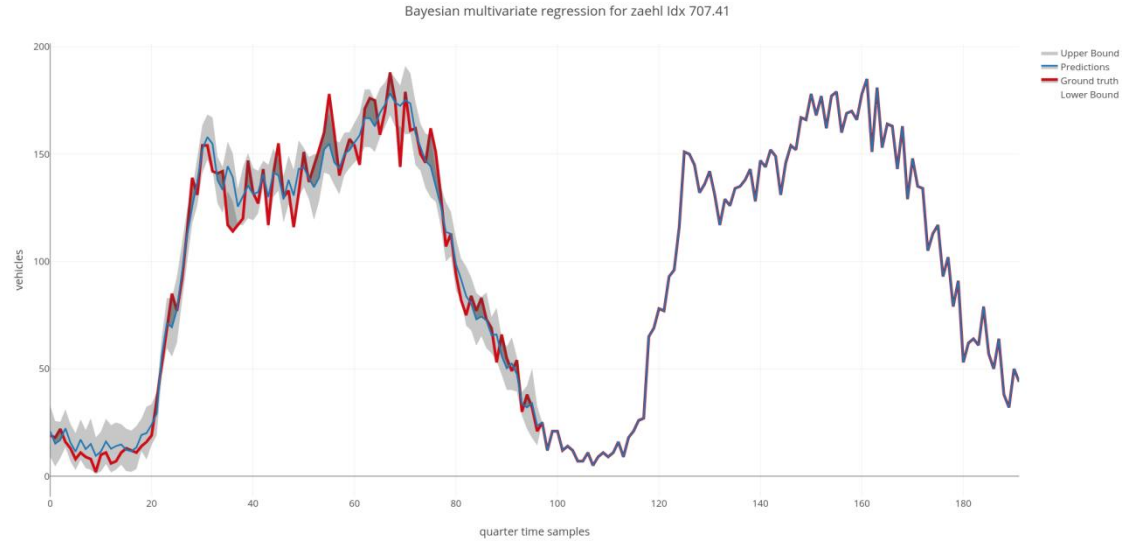


- Split data set per year
- Multiple Imputation by Chained Equation [6]
(MICE)
 - Imputation phase
 - Bayes Regression
 - Analysis phase
 - Calculate statistics like mean and variance
 - Pooling phase
 - Calculates the overall estimation of the imputed values

[6] Buuren, S van and Karin Groothuis-Oudshoorn (2010). “mice: Multivariate imputation by chained equations in R.”
In: Journal of statistical software, pp. 1–68

- Validation on each of the three models
- Randomly remove a given percentage of non missing values
- RMSE as validation score
- Stable RMSE by different missing value rates

hyper parameter	model		
	2015	2016	2017
number_nearest_features	20	20	20
max_imputation_cycles	10	10	10
diff_variance_threshold	-	-	-
nr_multiple_imputation	10	10	10

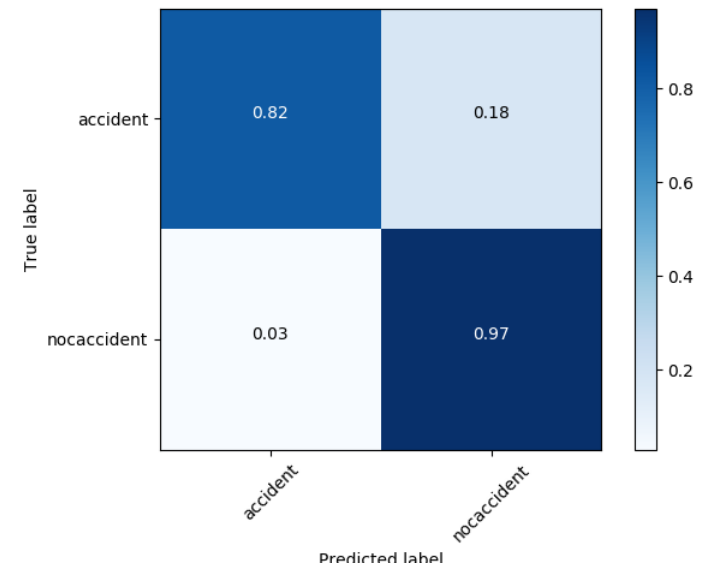
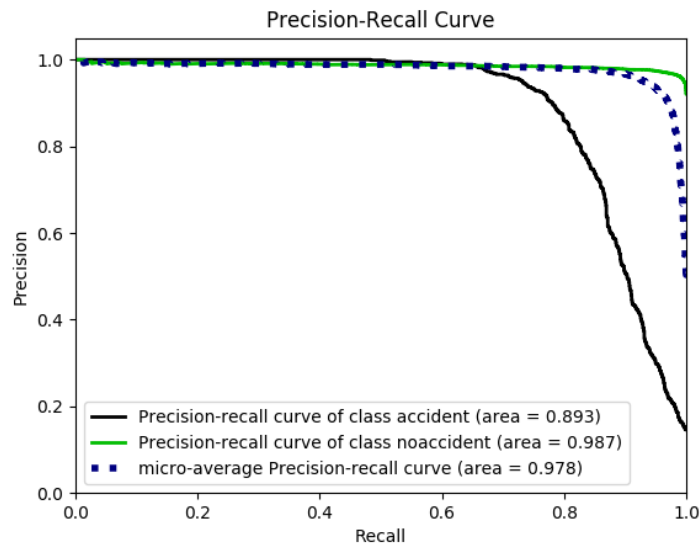


- Imbalanced classification problem
- Negative samples
 - Minority oversampling with matching rules [7]
- With and without sparse, pointwise traffic flow measurements

feature name	feature type	details	data source
accident_date	categorical	01.01.2015 - 31.12.2017	Crash data set
accident_time	categorical	24 categories	
is_holiday	categorical	2 categories	
road_condition	categorical	5 categories	
is_junction	categorical	2 categories	GIP graph
max_speed	numerical	0-80 km/h	
average_speed	numerical	0-100 km/h	
number_lanes	numerical	0-6 lanes	
road_width	numerical	0-22 meters	
road_surface	categorical	2 categories	
centrality	numerical	0 - 1	
curvature	numerical	1 - 2	Open Data Graz
slope	numerical	0% - 18.56%	
district	categorical	17 categories	
population_density	numerical	663 - 10423 resident per km^2	ZAMG data
temperature	numerical	-14.3°C - +33.3°C	
precipitation	numerical	0 - 15.1 mm	

[7] Ke, Jintao et al. (2019). "PCA-based missing information imputation for real-time crash likelihood prediction under imbalanced data." In: Trans-portmetrica A: transport science 15.2, pp. 872–895

- Gradient Boosting Classifier [8] (XGBoost)
 - Without traffic flow measurements
 - Random Grid Search
 - Hyper parameter search based on the F1 score

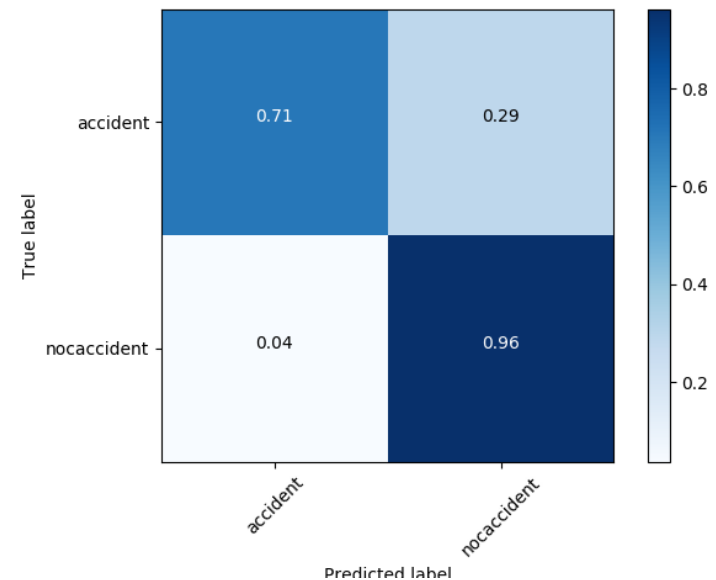
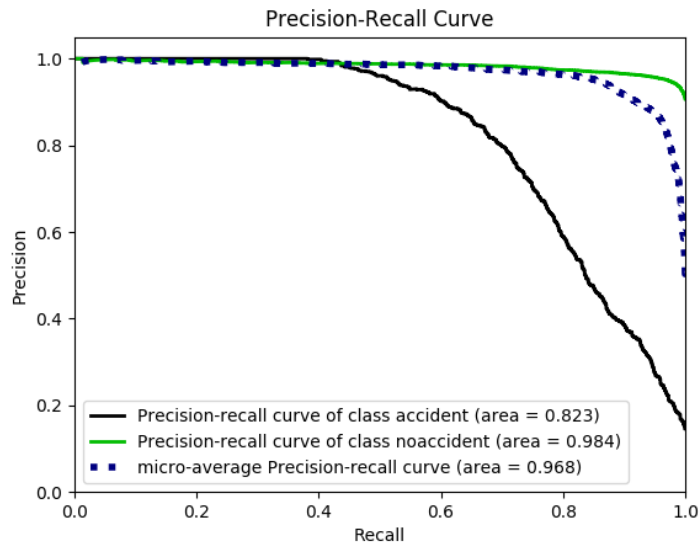


[8] XGBoost <https://xgboost.readthedocs.io/en/latest/> (Accessed on: 2020-03-08)

- Feature Importance
 - Gain importance metric
 - Permutation importance / Ablation study
 - F1 score: 0.82

permuted feature	F1 score
datetime	0.73
centrality	0.59
curvature	0.63
slope	0.64
width	0.66
number of lanes	0.69
population density	0.71
district	0.78
precipitation	0.81
temperature	0.82

- Gradient Boosting Classifier (XGBoost)
 - With pointwise traffic flow measurements



- Data processing
 - Temporal and spatial data sources
 - Feature Engineering and Map Matching
 - Exploratory data analysis
- Missing value imputation
 - MICE
 - Quality of imputed values depend on flow pattern
- Crash likelihood prediction
 - Negative sampling
 - XGBoost classification
 - Pointwise traffic flow values
- Future Work
 - City wide traffic flow estimation
 - Additional data sources

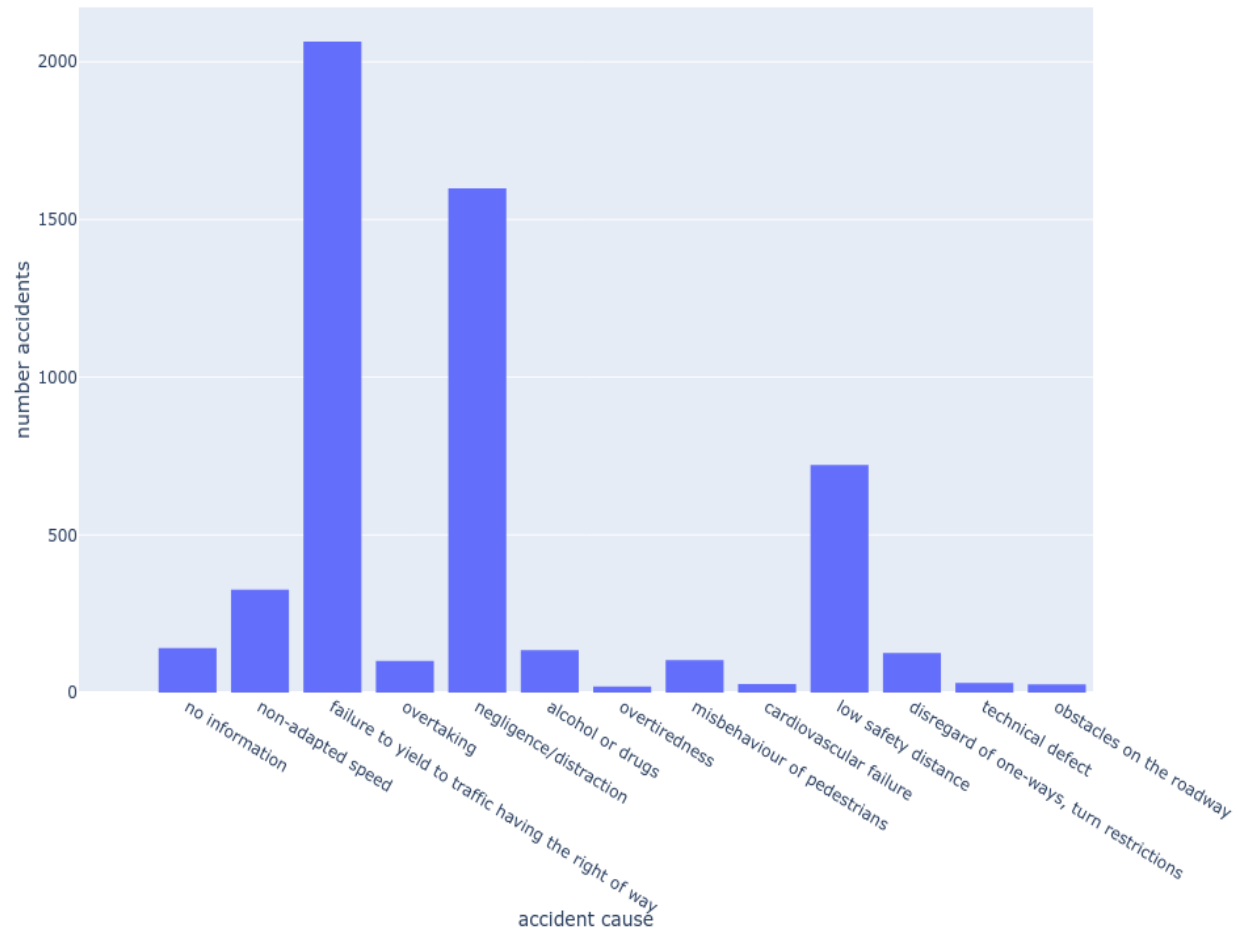
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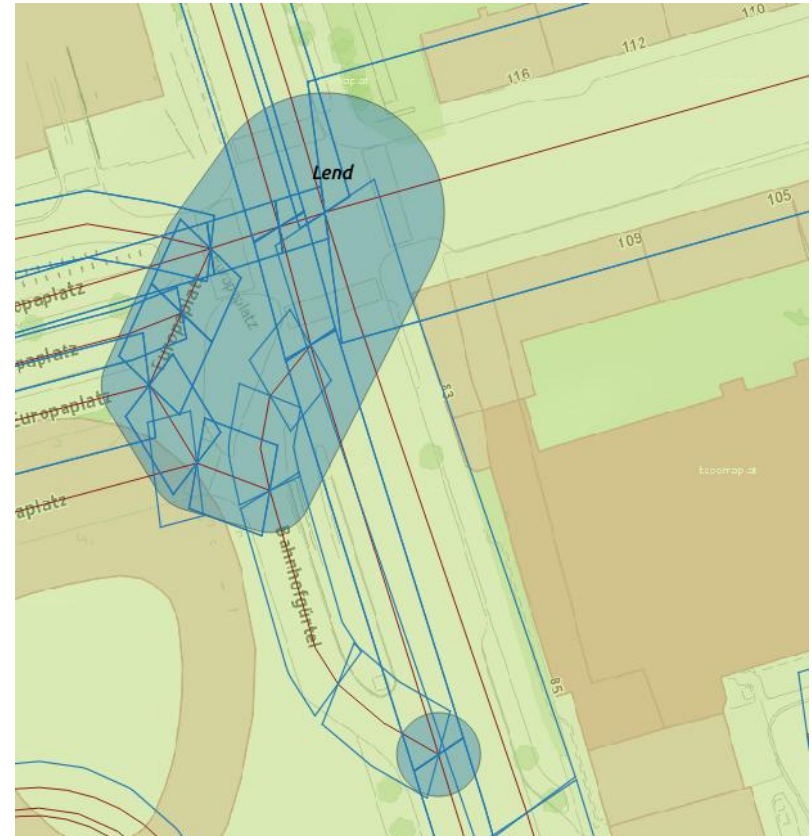
Backup Material



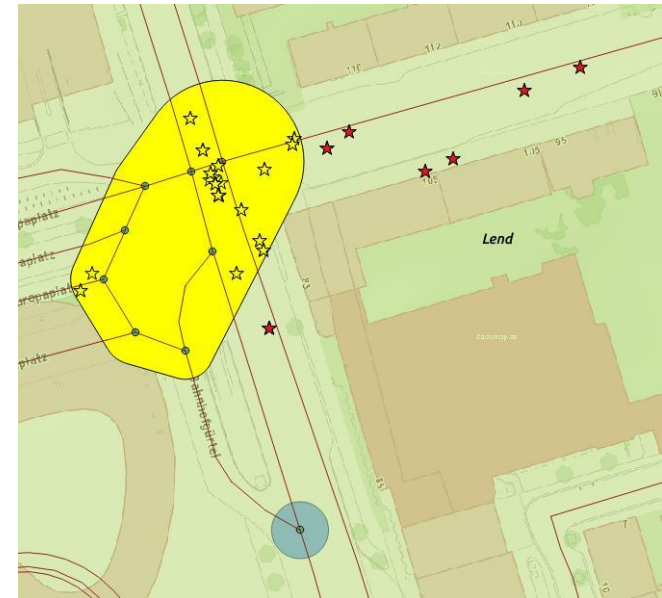
- Gemäß § 2 Abs 1 Z 17 StVO ist eine Kreuzung eine Stelle, auf der eine Straße eine andere überschneidet oder in sie einmündet, gleichgültig in welchem Winkel. Die Schnittpunkte der gedachten Straßenbaulinien bilden dabei die Eckpunkte des Kreuzungsbereichs und die gedachten Verlängerungen der Straßenbaulinien grenzen den Kreuzungsbereich ab



Junction definition



GIP ID	road name	number accidents
201005262	Joanneumring	24
201007193	Annenstraße	18
201007177	Keplerstraße	17
201000754	Kärntnerstraße	15
101571709	Lazarettgürtel	14
101374559	Conrad-von-Hötzendorf-Straße	14



- Spatial interpolation method for high variable data sets

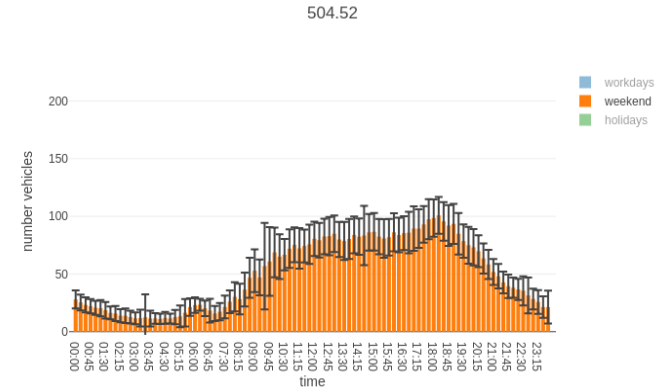
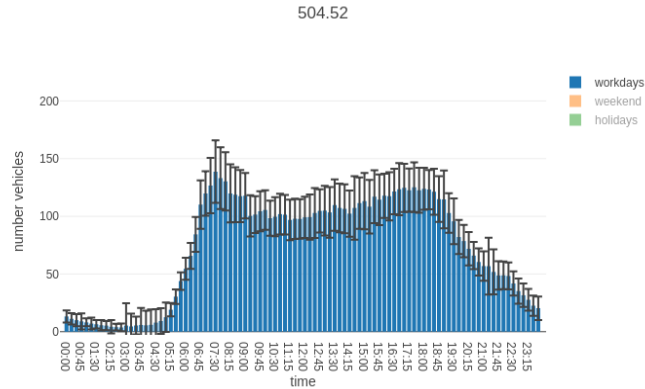
$$u(x) = \sum_{k=1}^N \frac{w(x, x_k)}{\sum_{j=1}^N w(x, x_j)} u_k$$

Where $u(x)$ is the interpolation value of a point x based on known samples $u_k = u(x_k)$ for $k = 1, 2, \dots, N$.
 $w(x, x_k)$ represents the weighting function

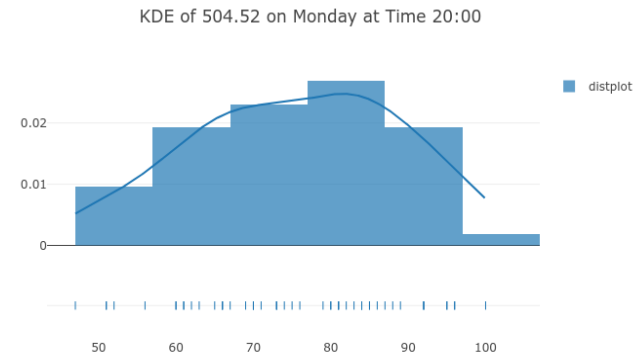
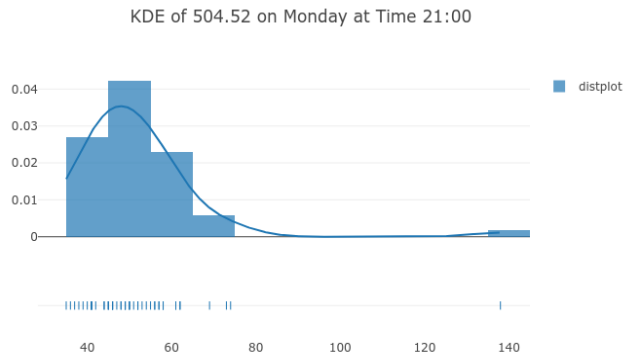
$$w(x, x_k) = \frac{1}{d(x, x_k)^p} \quad (3.2)$$

Where d stands for a given distance metric, typically the Euclidean distance, between x and x_k .

- Workday and weekend pattern

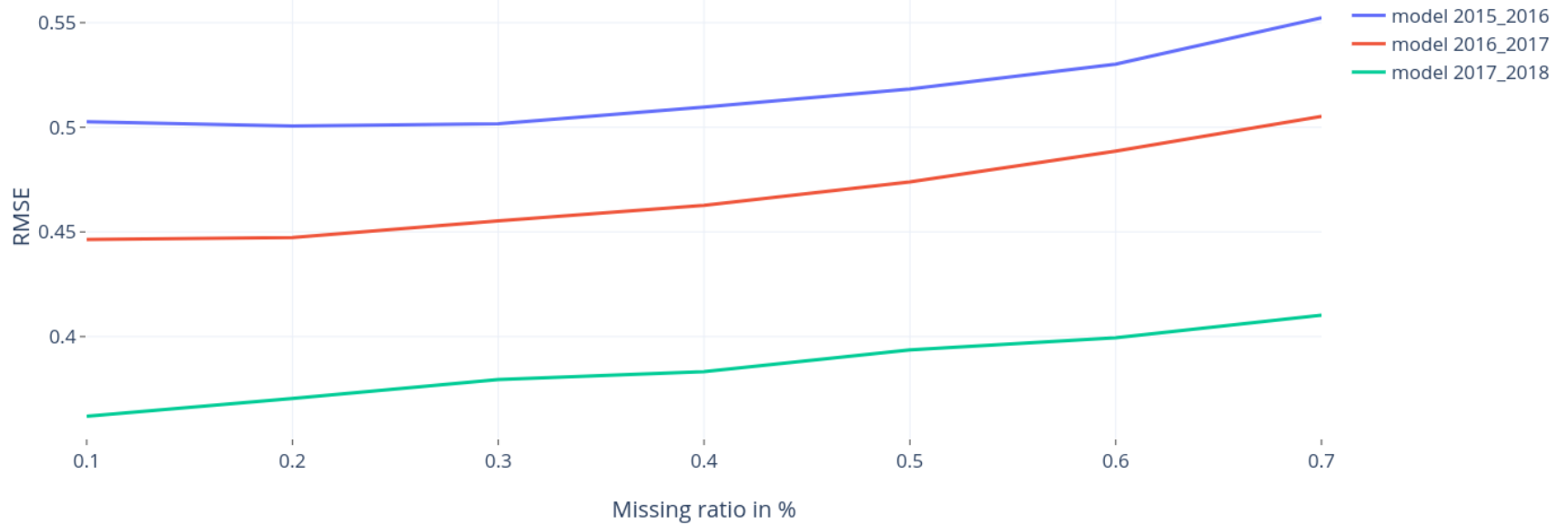


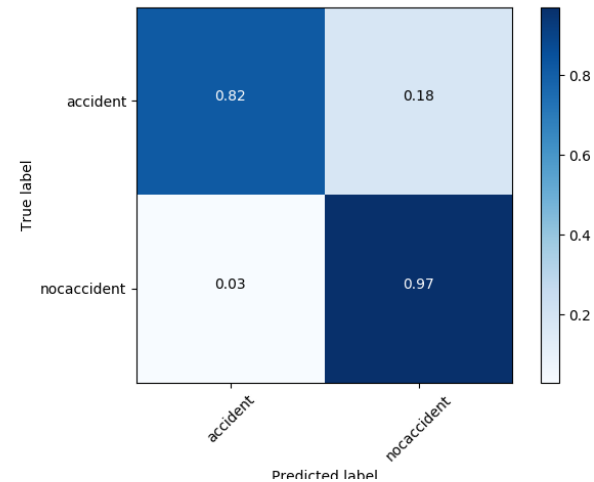
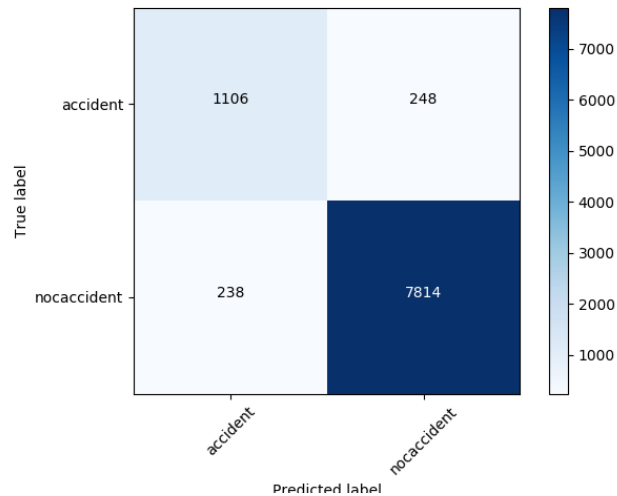
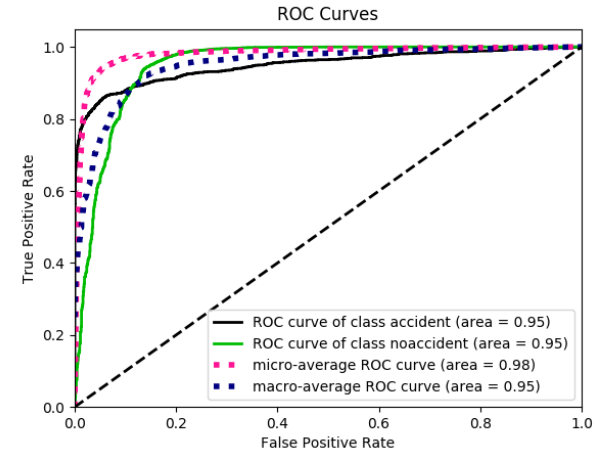
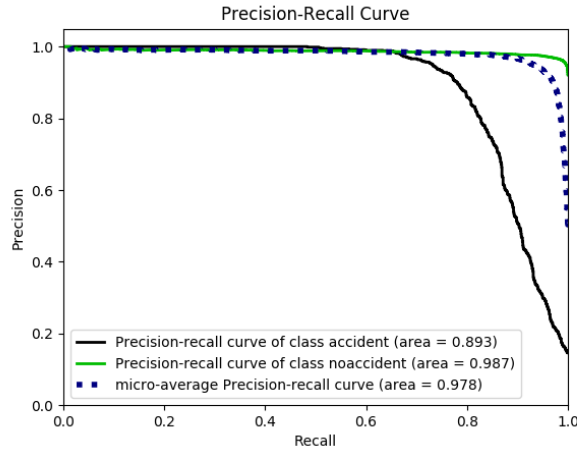
- Distribution over different daily timestamps



- In the first imputation step, all missing values are masked so that for further turns the imputed values still can be recognized and the mean over X_j^{obs} is imputed. These imputation can be thought of as place holders.
- In the second step, the place holder mean imputations for X_j is set back to missing.
- In the third step X_j^{mis} are regressed on X_{-j} via the *BayesRidgeRegression* approach. Not all X_{-j} features are taken for imputation but just the n strongest correlated feature vectors. The Pearson correlation coefficient is used for estimating these n vectors.
- In the fourth step the missing values X_j^{mis} are replaced with the regressed values.
- In step five step two to step four is repeated for all X_j^{miss} with ($j = 1, \dots, p$)
- In step six the imputation process as stated in step 5 is repeated for a given number of cycles with the imputations being updated at each cycle.

- Estimated Value $\theta_{MI} = \frac{1}{M} \sum_{i=1}^M \theta_i$
- Within Variance $Var_{within} = \frac{\sum_{i=1}^M SE_i^2}{M}$
- Between Variance $Var_{between} = \frac{\sum_{i=1}^M (\theta_i - \theta_{MI})^2}{M - 1}$
- Total Variance $Var_{MI} = Var_{within} + (1 + \frac{1}{M}) Var_{between}$





- Hyper parameters

hyper-parameter	estimated value
objective	binary:logistic
learning_rate	0.1
max_depth	10
min_child_weight	2
subsample	1
colsample_bytree	0.7
n_estimators	350

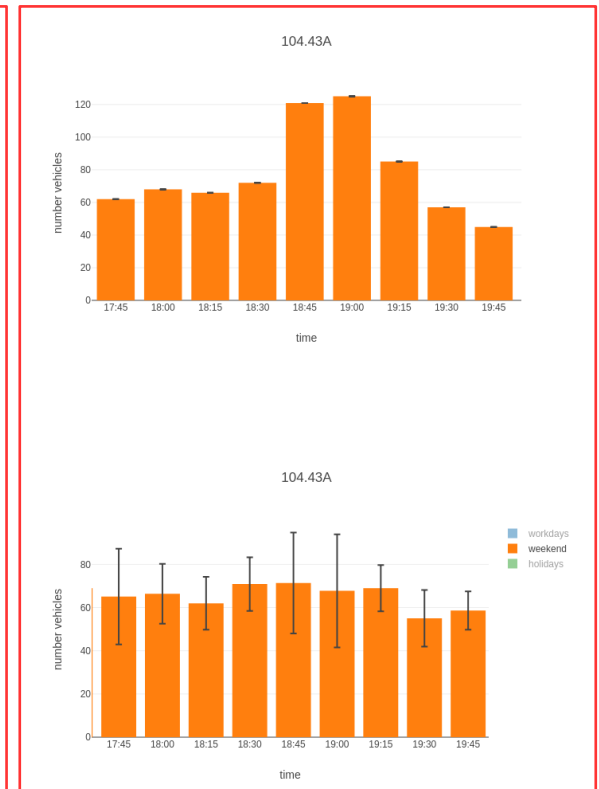
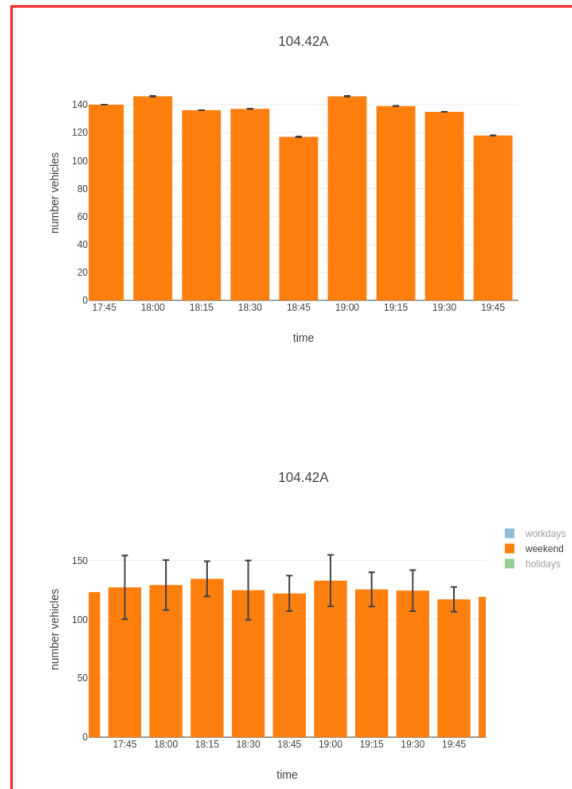
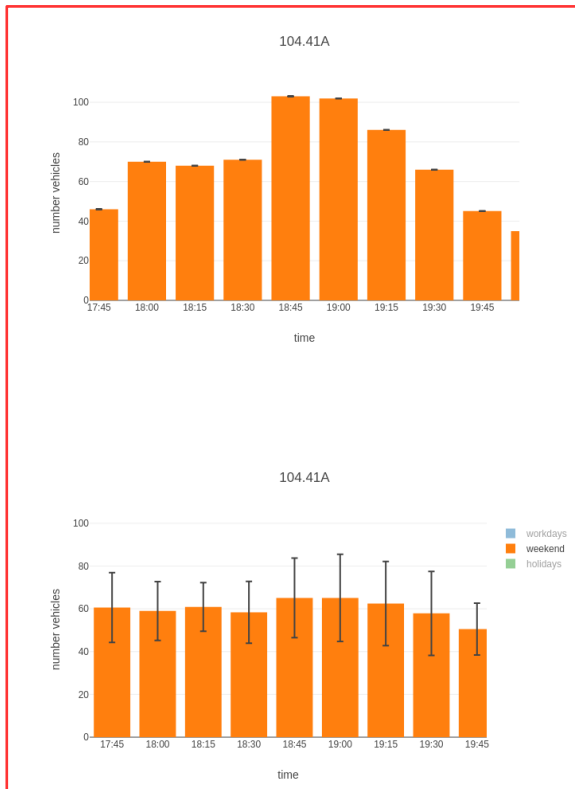
test set	threshold for class non-accident	precision	recall	accuracy	f1-score
sample over three years	>50%	0.98	0.61	0.94	0.76
	>85%	0.82	0.81	0.95	0.82
year 2017	>50%	0.90	0.63	0.94	0.74
	>85%	0.62	0.82	0.90	0.71

Result without pointwise traffic flow measurements

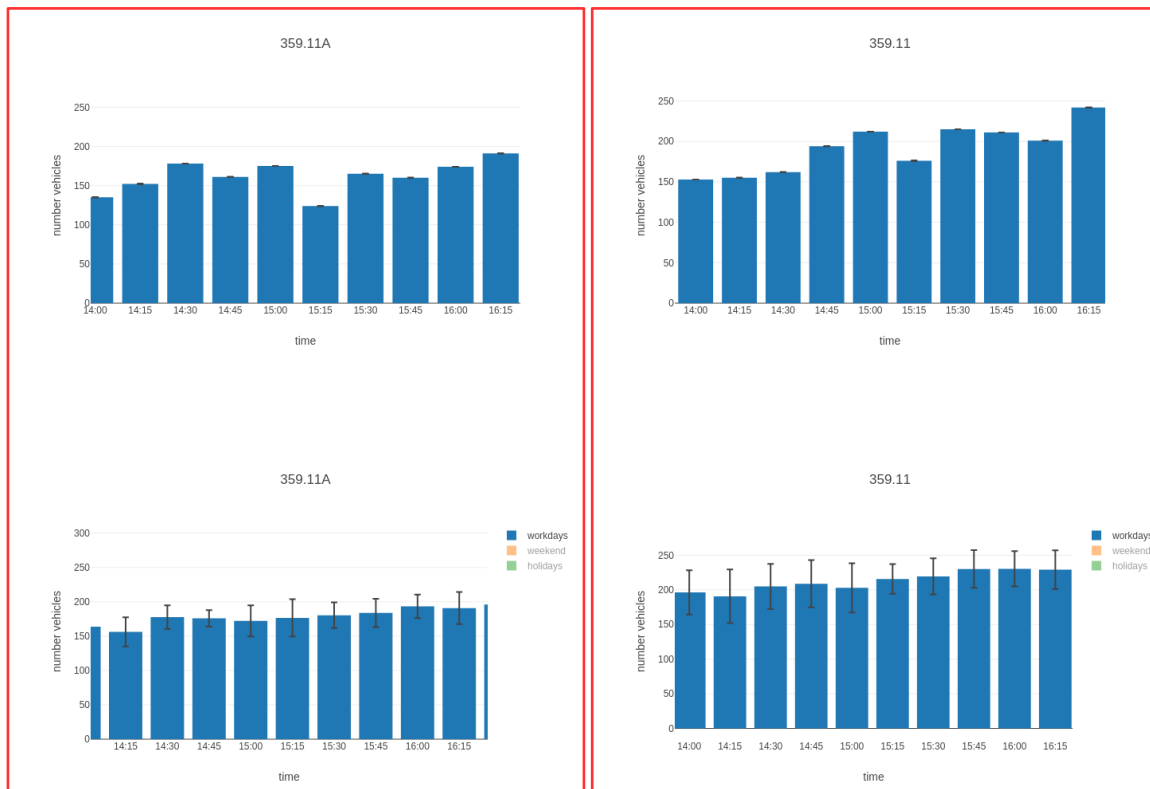
test set	prediction threshold for class non-accident	precision	recall	accuracy	f1-score
sample over three years	>50%	1.0	0.39	0.91	0.53
	>94%	0.76	0.71	0.93	0.74
year 2017	>50%	0.91	0.41	0.91	0.57
	>94%	0.36	0.84	0.76	0.51

Result with pointwise traffic flow measurements

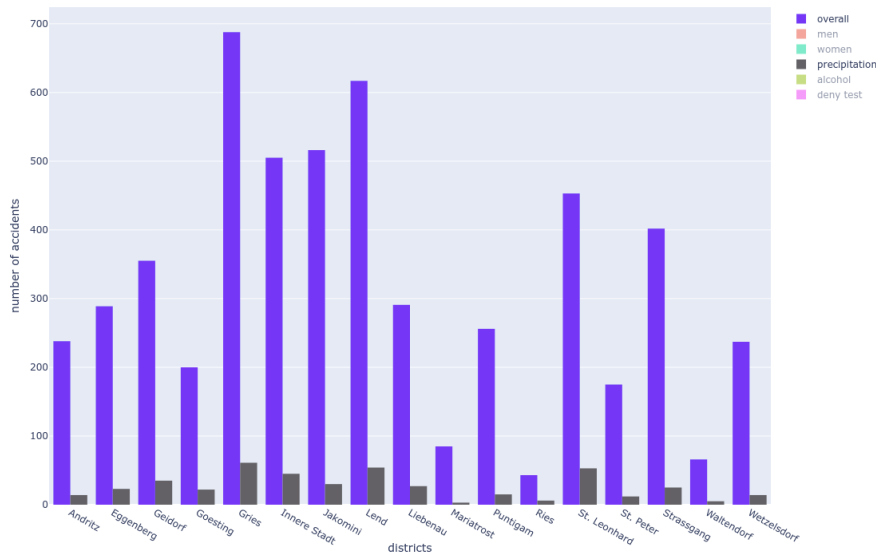
- Joanneumring
 - One-way street with 3 lanes
- Accidentth
 - 7th May 2017 at 06:45 p.m.



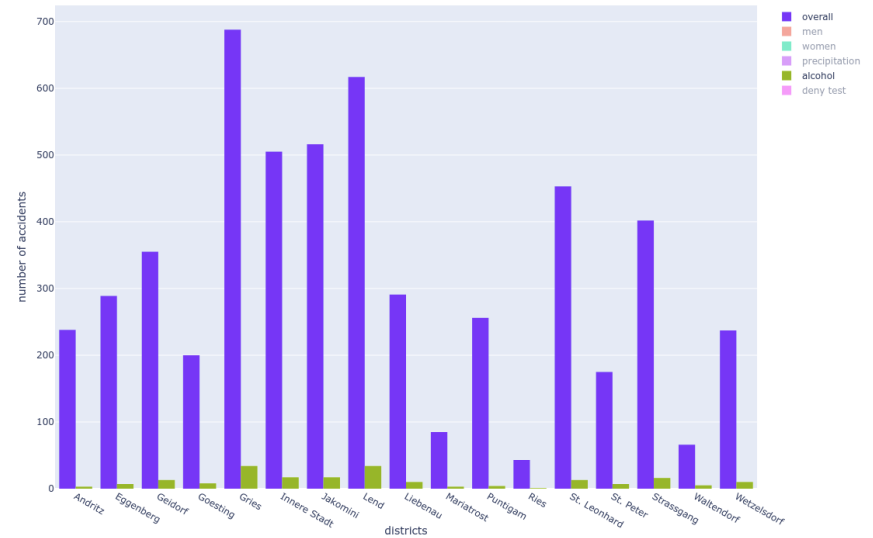
- Weinzöttlstraße
 - One-way street with 2 lanes
- Accident
 - 27th May 2017 at 03:00 p.m.



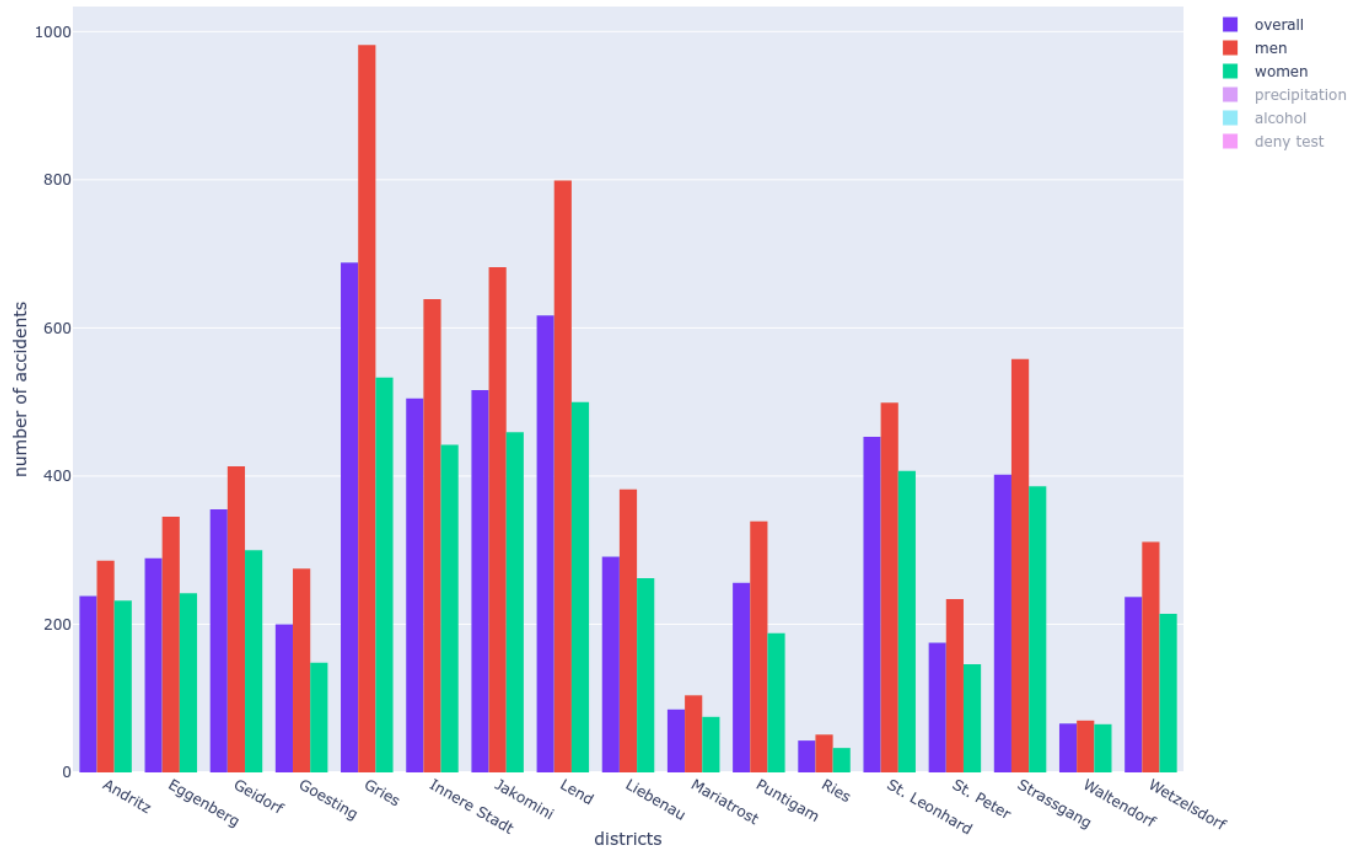
- Beginning rainfall / snowfall
 - Aggregated in 1 hour intervals
 - Prior hour no precipitation measured
- Statistics
 - 710 accidents between 2015 – 2017
 - 184 accidents by beginning precipitation
 - $P(\text{start precipitation}) = 2.45\%$
 - $P(\text{start precipitation}|\text{accident}) = 3.4\%$



Accidents under precipitation



Accidents under alcohol influence



Number of accident participants per gender